

Designing Local Algorithms with Algorithms

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Joint work with...

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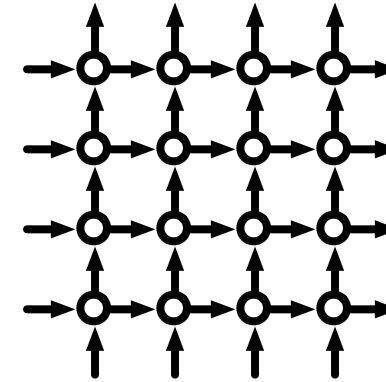
Orr Fischer (Tel Aviv)

Algorithm synthesis

- Computer science: what can be automated?
- Can we *automate our own work*?
- Can we outsource algorithm design to computers?
 - **input:** problem specification
 - **output:** asymptotically optimal algorithm

Today: a success story

- Case study:
 - computational design of local distributed algorithms for **LCL problems** on **grid graphs**
- Spoiler:
 - undecidable – but with one bit of advice we can do it!
 - *not just in theory but also in practice*



Setting

- Distributed graph algorithms
- *Input graph = computer network*
 - node = computer, edge = communication link
 - unknown topology
- Each node outputs its own part of solution
 - e.g. graph colouring: node outputs its own colour

Setting

- Deterministic distributed algorithms,
LOCAL model of computing
 - unique identifiers
 - synchronous communication rounds
 - *time = number of rounds* until all nodes stop
 - unlimited message size,
unlimited local computation

Setting

- Deterministic distributed algorithms, **LOCAL** model of computing
- Time = distance
- Algorithm with running time T :
mapping from radius- T neighbourhoods to local outputs

LCL problems

- **LCL = locally checkable labelling**
 - Naor–Stockmeyer (1995)
- Valid solution can be detected by checking $O(1)$ -radius neighbourhood of each node
 - maximal independent set, maximal matching, vertex colouring, edge colouring ...

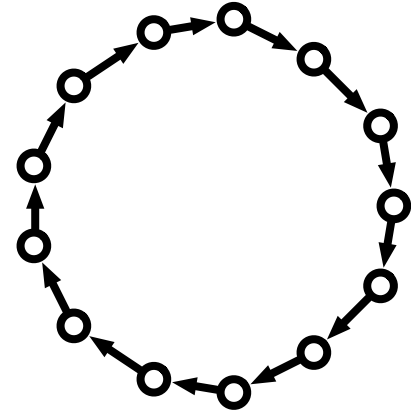
LCL problems

- All LCL problems can be solved with $O(1)$ -round *nondeterministic* algorithms
 - guess a solution, verify it in $O(1)$ rounds
- Key question: how fast can we solve them with *deterministic* algorithms?
 - cf. P vs. NP

Traditional settings

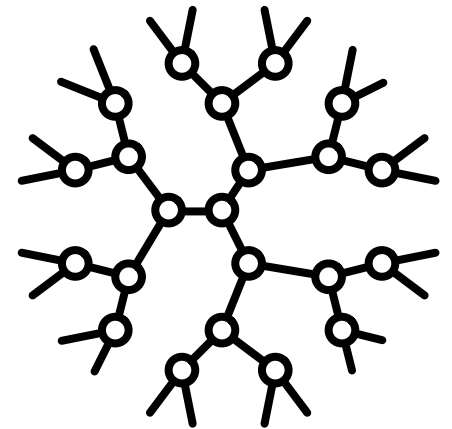
- **Directed cycles**

- Cole–Vishkin (1986), Linial (1992)...
- well understood

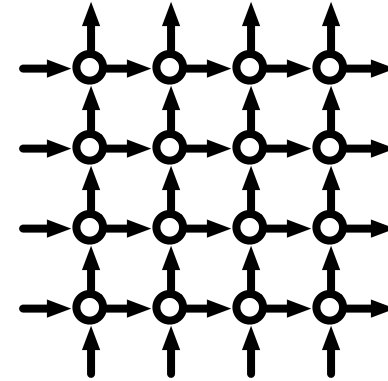


- **General (bounded-degree) graphs**

- lots of ongoing work...
- typical challenge:
expander-like constructions

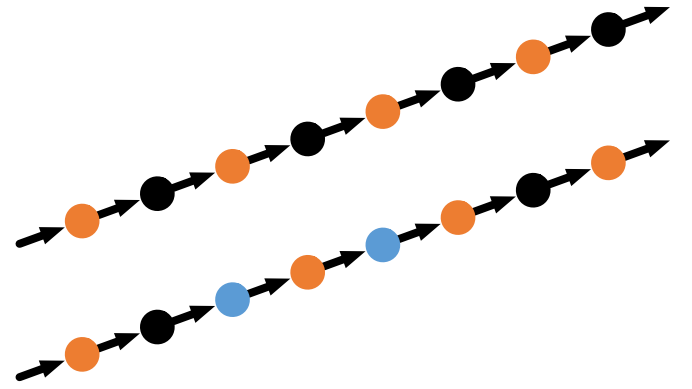


Our setting today



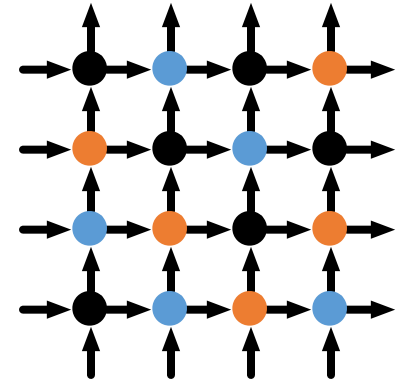
- **Oriented grids** (2D)
 - toroidal grid, $n \times n$ nodes, unique identifiers
 - consistent orientations north/east/south/west
- **Generalisation of directed cycles** (1D)
- Closer to real-world systems than expander-like worst-case constructions?

Warm-up examples



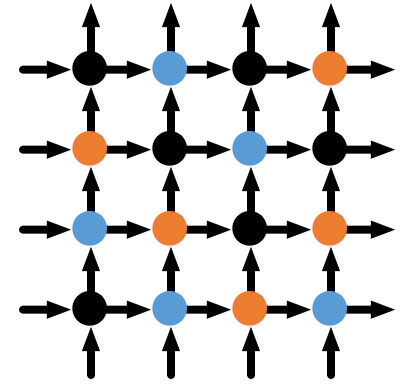
- Vertex colouring in **1D grids**
- **2-colouring**: global, $\Theta(n)$ rounds
- **3-colouring**: local, $\Theta(\log^* n)$ rounds
 - Cole–Vishkin (1986), Linial (1992)

Warm-up examples



- Vertex colouring in **2D grids**
- **2-colouring**: global, $\Theta(n)$ rounds
- **3-colouring**: ???
- **4-colouring**: ???
- **5-colouring**: local, $\Theta(\log^* n)$ rounds

Warm-up examples



- Vertex colouring in **2D grids**
- **2-colouring**: global, $\Theta(n)$ rounds
- **3-colouring**: global, $\Theta(n)$ rounds
- **4-colouring**: local, $\Theta(\log^* n)$ rounds
- **5-colouring**: local, $\Theta(\log^* n)$ rounds

Warm-up examples

- Vertex colouring in **4-regular graphs**
- **2-colouring**: global, $\Theta(n)$ rounds
- **3-colouring**: global, $\Theta(n)$ rounds
- **4-colouring**: intermediate, **polylog** rounds
- **5-colouring**: local, $\Theta(\log^* n)$ rounds

Complexity of LCL problems

- 1D grids:
 - everything is $O(1)$, $\Theta(\log^* n)$, or $\Theta(n)$
 - **decidable**
- Bounded-degree graphs:
 - intermediate complexities, **polylog(n)** ... (Brand et al. 2016)
 - **undecidable** (Naor–Stockmeyer 1995)

Complexity of LCL problems

- 1D grids:
 - everything is $O(1)$, $\Theta(\log^* n)$, or $\Theta(n)$
 - **decidable**
- 2D grids:
 - everything is $O(1)$, $\Theta(\log^* n)$, or $\Theta(n)$
 - **undecidable**

Complexity of LCL problems

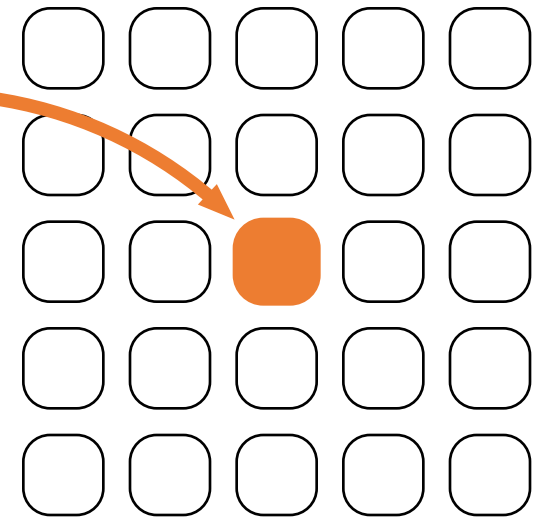
- 1D grids:
 - everything is $O(1)$, $\Theta(\log^* n)$, or $\Theta(n)$
 - **decidable**
- 2D grids:
 - everything is $O(1)$, $\Theta(\log^* n)$, or $\Theta(n)$
 - **undecidable — but let us not despair!**

Goal: algorithm synthesis

- Setting:
 - **input:** specification of an LCL problem
 - **output:** asymptotically optimal algorithm for 2D grids
- *Does this make any sense?*
 - most interesting case: $\Theta(\log^* n)$ time
 - how could one even represent an arbitrary $\Theta(\log^* n)$ -round algorithm in a computer??

92	33	77	57	49	26	74
71	79	8	62	48	24	55
31	21	15	30	60	67	3
0	5	17	95	23	47	98
87	80	25	38	20	64	88
45	61	91	51	69	1	99
58	53	63	40	16	2	39

A



$O(\log^* n)$

Goal: algorithm synthesis

- $\Theta(\log^* n)$ -round algorithm in 2D grids:
 - mapping from $\Theta(\log^* n) \times \Theta(\log^* n)$ neighbourhoods to local outputs
 - nodes are labelled with $1, 2, \dots, \text{poly}(n)$
- *Infinite family of functions*
- Awkward to handle with computers

Key insight: normalisation

- **Setting:** LCL problems, 2D grids
- **Theorem:** Any $\Theta(\log^* n)$ -time algorithm can be translated to a “*normal form*”
 - we isolate a fixed $\Theta(\log^* n)$ -time component
 - everything else is a *finite function*

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$O(\log^* n)$

MIS

0	0	0	1	0	0	1
0	1	0	0	1	0	0
0	0	1	0	0	0	1
1	0	0	0	1	0	0
0	0	1	0	0	1	0
0	1	0	0	1	0	0
0	0	1	0	0	0	1

$O(1)$

f



Key insight: normalisation

- For *any problem P* of complexity $\Theta(\log^* n)$, there are **constants k and r** and function f such that P can be solved as follows:
 - input: 2D grid G with unique identifiers
 - find a *maximal independent set in G^k*
 - *discard unique identifiers*
 - apply function f to each $r \times r$ neighbourhood

Some proof ideas

- Given: A solves P in time $o(n)$ in $n \times n$ grids
- Solving P in time $O(\log^* N)$ in $N \times N$ grids:
 - pick suitable $n = O(1)$, $k = O(1)$
 - find MIS in G^k
 - use MIS to find *locally unique identifiers* for $n \times n$ neighbourhoods
 - simulate A in $n \times n$ local neighbourhoods

Normalisation in practice

- Example: **4-colouring**
- Sufficient to pick $k = 3$, $r = 7$
- Algorithm \approx mapping $\{0, 1\}^{7 \times 7} \rightarrow \{1, 2, 3, 4\}$
 - only finitely many candidates
 - given a candidate, we can easily verify if it is good

What about undecidability?

- **Trivial case:** complexity $O(1)$
- **Undecidable:** given an LCL problem, is its complexity $\Theta(\log^* n)$ or $\Theta(n)$ in 2D grids?
- However, if we get just *one bit of advice* (or make a lucky guess), we can find an asymptotically optimal algorithm!

Synthesis with advice

- **Advice:** complexity is $\Theta(\log^* n)$
 - try each pair (r, k)
 - check if there is a valid mapping from binary $r \times r$ matrices that represent local parts of maximal independent sets in G^k
- **Advice:** complexity is $\Theta(n)$
 - trivial brute force is optimal

It works in practice, too!

- **Ongoing work:** we have already synthesised asymptotically optimal algorithms for *thousands* of LCL problems
 - “high-throughput algorithm design”
 - can gain insights into the structure of large families of *parametrised problems*
 - synthesis unsuccessful: conjecture lower bound?

Some building blocks

- Enumerate all $r \times r$ neighbourhoods that represent possible fragments of maximal independent sets in G^k
- Construct neighbourhood graphs
 - algorithm \approx labelling of neighbourhood graph
- Apply SAT solvers to find a labelling

Human beings still needed

- Computers can design e.g. very efficient algorithms for 4-colouring
- We still needed human beings to prove that there is **no algorithm for 3-colouring**
 - *new lower-bound techniques* needed, but more about this in some other talk!

Conclusions

- Nontrivial algorithms: $\Theta(\log^* n)$ complexity
- Any such algorithm can be split in two parts:
 - “**symmetry breaking**”: find an MIS
 - “**computation**”: nontrivial but finite
- Main open question: *how far can we push this beyond oriented 2D grids?*

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87	80	25	38	20	64	88
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$O(\log^* n)$

MIS

0	0	0	1	0	0	1
0	1	0	0	1	0	0
0	0	1	0	0	0	1
1	0	0	0	1	0	0
0	0	1	0	0	1	0
0	1	0	0	1	0	0
0	0	1	0	0	0	1

$O(1)$

f

