

Fast Variational Bayesian Linear State-Space Model

Jaakko Luttinen, jaakko.luttinen@aalto.fi
Department of Information and Computer Science, Aalto University

Summary

- *Model*: Linear state-space model
 - used for multivariate dynamical systems
- *Problem*: Variational Bayesian (VB) estimation is slow because
 - the variables are strongly coupled
 - the variables are updated one at a time
 - the iteration zigzags and proceeds slowly
- *Solution*: Jointly optimize several variables based on how they are coupled
 - that is, optimize the rotation of the latent subspace
 - in general, known as parameter expansion
- *Effect*: 100–10000 times faster convergence

Speed-up rotation / Parameter expansion

- Motivate the parameter expansion by the rotational ambiguity of the latent sub-space.
- The states can be rotated by compensating it in the loadings:

$$\mathbf{y}_n = \mathbf{C}\mathbf{x}_n = \mathbf{C}\mathbf{R}^{-1}\mathbf{R}\mathbf{x}_n,$$

thus rotate as $\mathbf{C} \rightarrow \mathbf{C}\mathbf{R}^{-1}$ and $\mathbf{x}_n \rightarrow \mathbf{R}\mathbf{x}_n$.

- Keep the dynamics of the latent states unaffected:

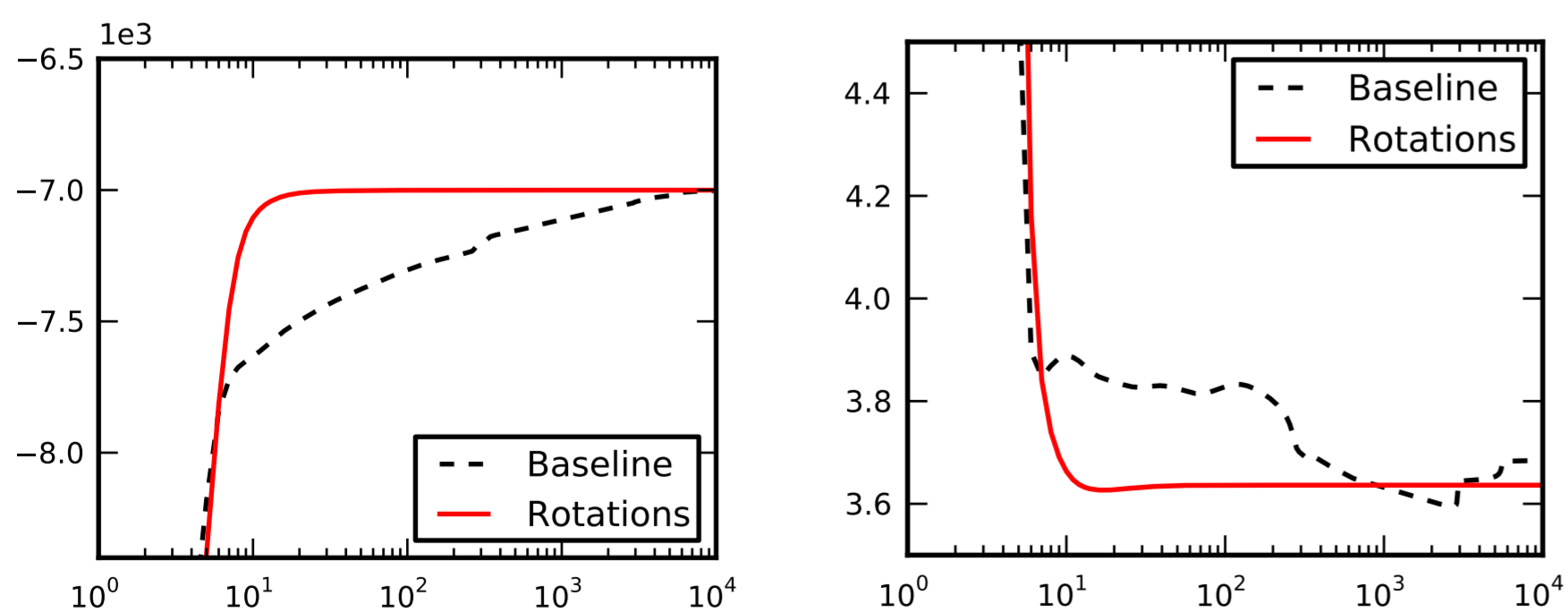
$$\mathbf{R}\mathbf{x}_n = \mathbf{R}\mathbf{A}\mathbf{R}^{-1}\mathbf{R}\mathbf{x}_{n-1},$$

thus rotate as $\mathbf{A} \rightarrow \mathbf{R}\mathbf{A}\mathbf{R}^{-1}$.

- Parameterize the VB posterior by \mathbf{R} and maximize the VB lower bound with respect to \mathbf{R} .

Artificial experiment

- 400 observations with 30 dimensions
- 8-dimensional latent space
- Performance as a function of VB iterations (log-scale):



(a) VB lower bound

(b) Test RMSE

Model

- A sequence of high-dimensional observations ($\mathbf{y}_1, \dots, \mathbf{y}_N$) is assumed to be generated from latent low-dimensional states ($\mathbf{x}_1, \dots, \mathbf{x}_N$):

$$\mathbf{y}_n = \mathbf{C}\mathbf{x}_n + \text{noise}.$$

where \mathbf{C} is the loading matrix

- The latent states follow a first-order Markov process:

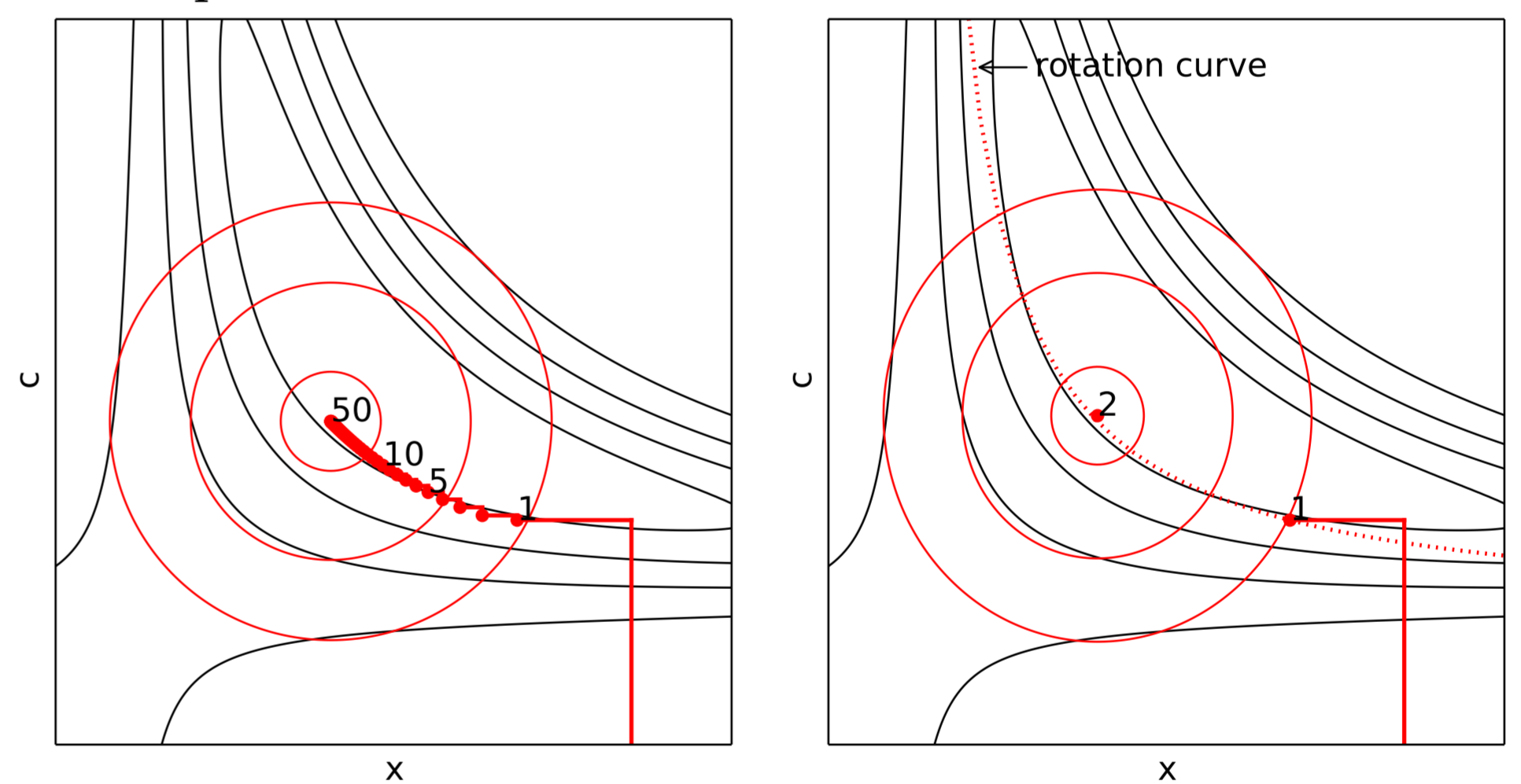
$$\mathbf{x}_n = \mathbf{A}\mathbf{x}_{n-1} + \text{noise}.$$

where \mathbf{A} is the state dynamics matrix.

- Variables \mathbf{x}_n , \mathbf{A} and \mathbf{C} are unknown and estimated from the data.

Simple illustration

- VB for a simple 1-dimensional model $y = cx + \text{noise}$
- Rotate as $x \rightarrow Rx$ and $c \rightarrow c/R$
- Compare the VB iterations with and without rotation:

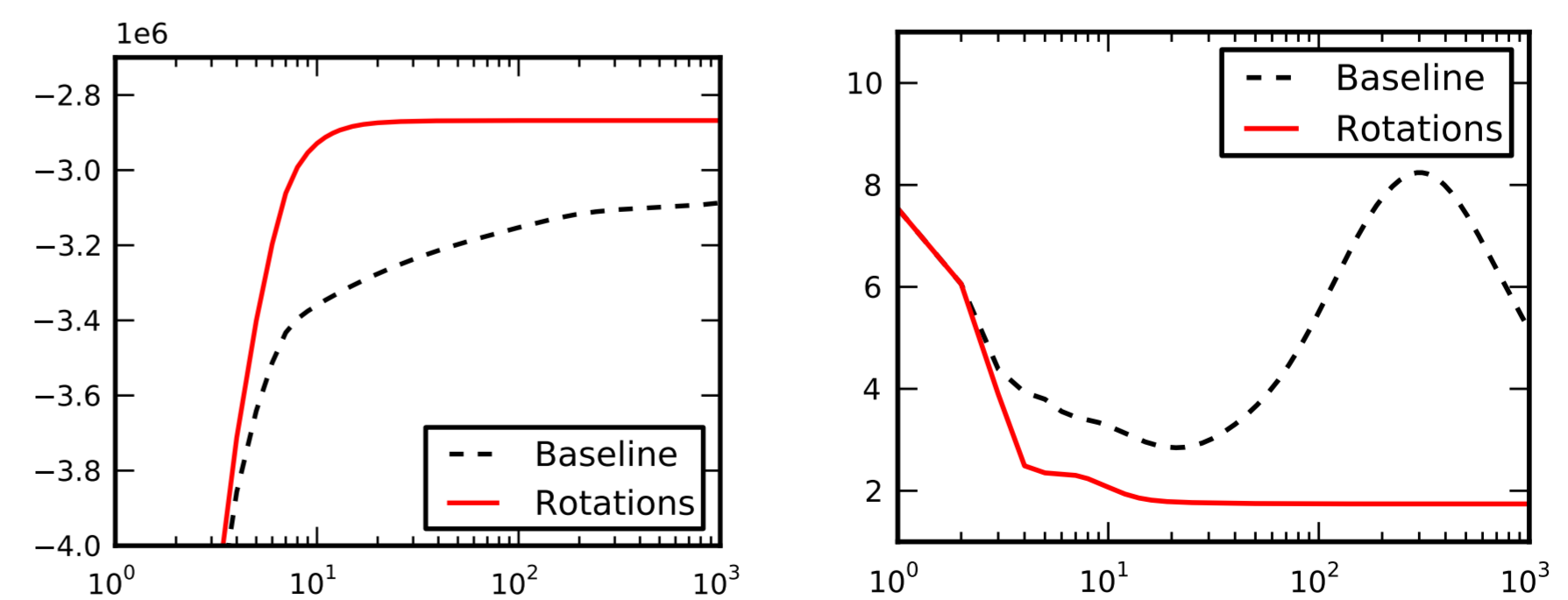


(a) Standard VB

(b) VB using rotations

Weather data experiment

- 89202 observations with 66 dimensions
- 10-dimensional latent space
- Performance as a function of VB iterations (log-scale):



(a) VB lower bound

(b) Test RMSE